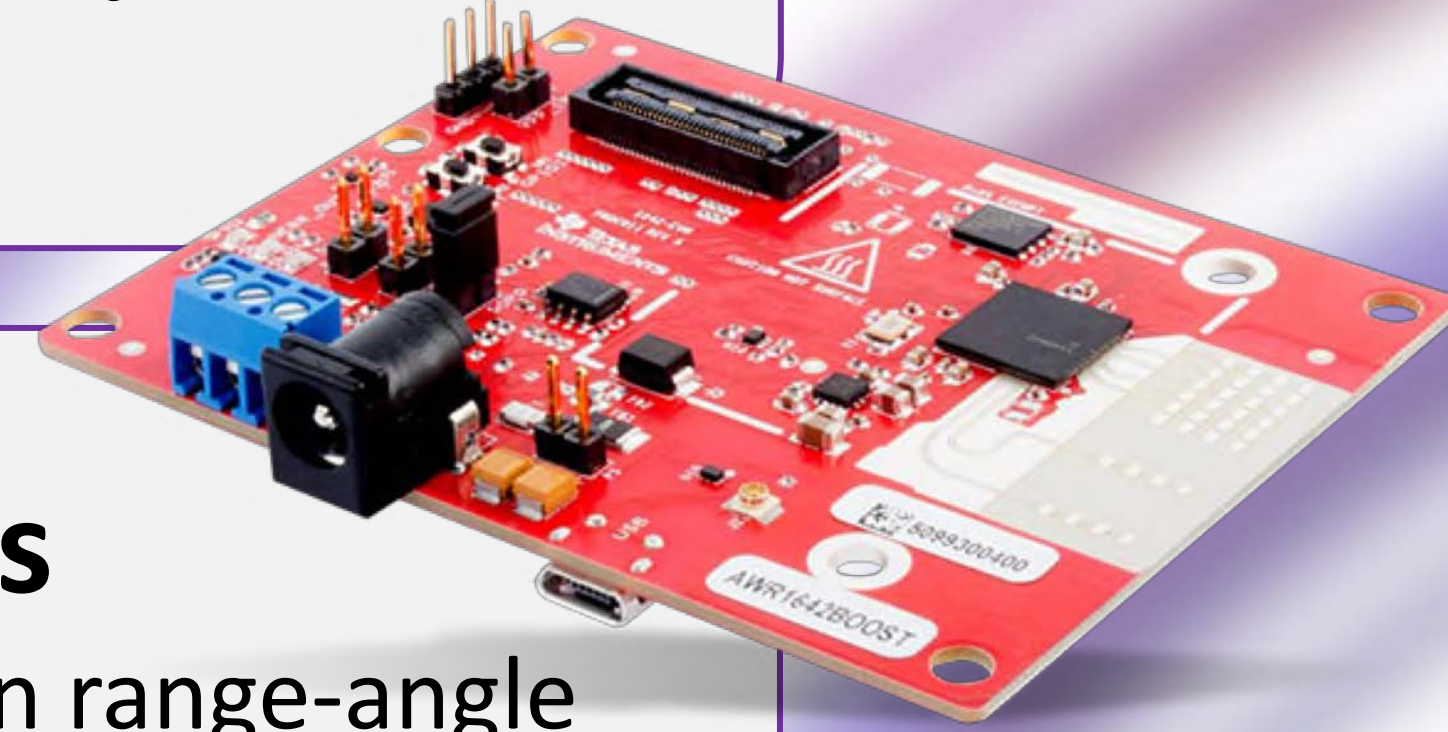


Yekaterina Mikhaylyuta & Matthew Sissel
 Faculty Advisor: Prof. Sumit Roy
 Industry Advisor: Chris Balton
 Sponsor: Paccar

Problem Statement

- Evaluate radar for automotive application
- Platform: TI-AWR1642BOOST
- Develop radar signal processing algorithms for object detection
- Create classifier to distinguish objects based on radar footprint

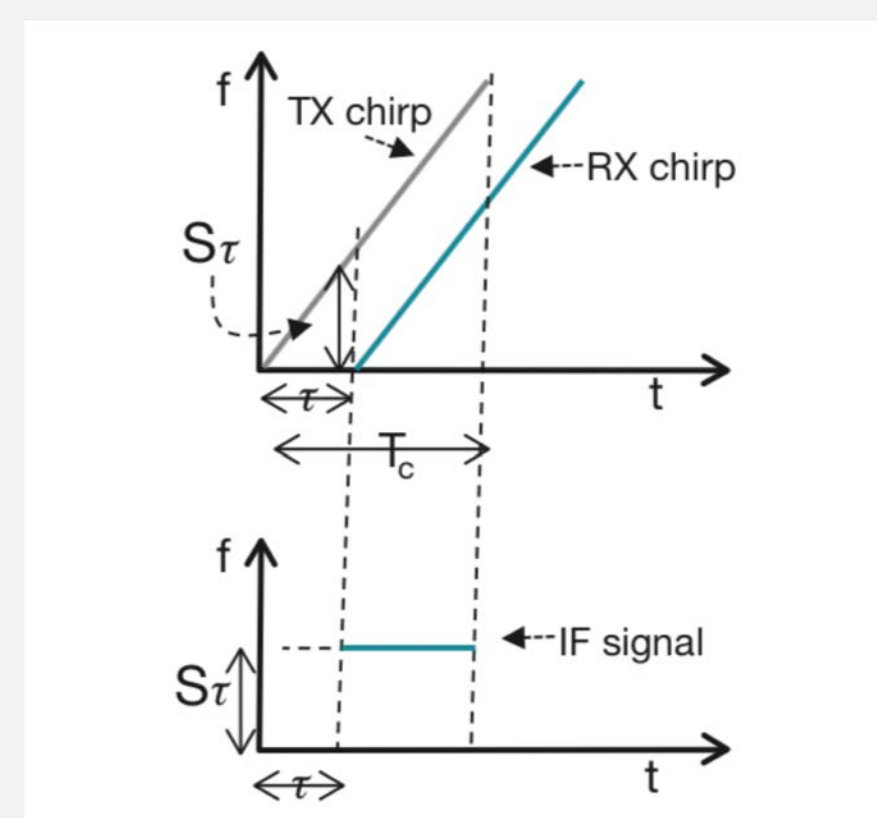


Requirements

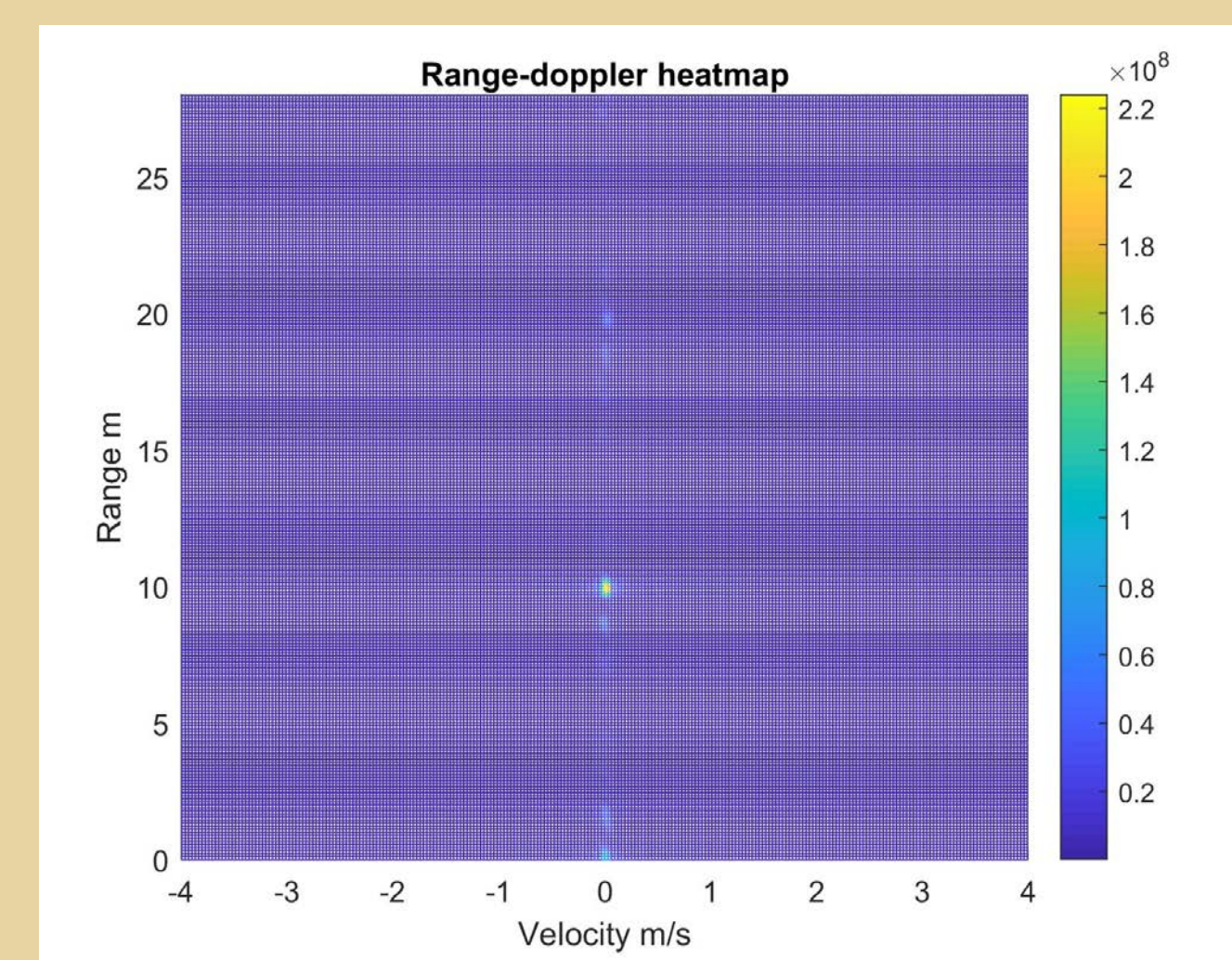
- Detect the position of object in range-angle heatmap
- Track the trajectory of object in simple scenario, e.g. one moving target.
- Detect the velocity of object and show the change of velocity with time.
- Easy-operating GUI to do signal processing
- Simple classifier for person and car.

Implementation

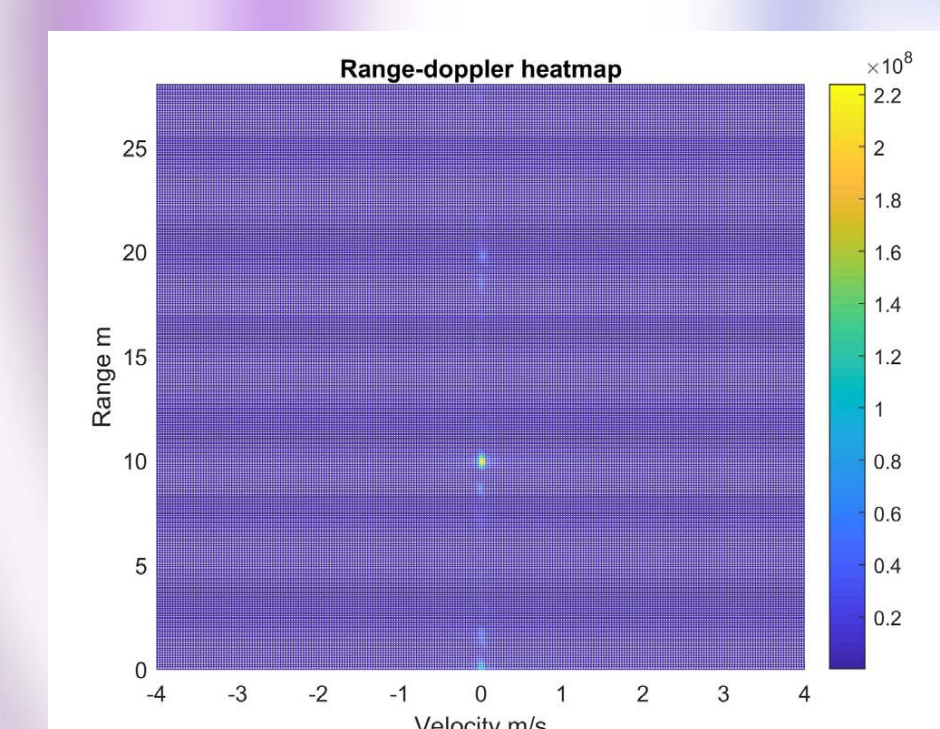
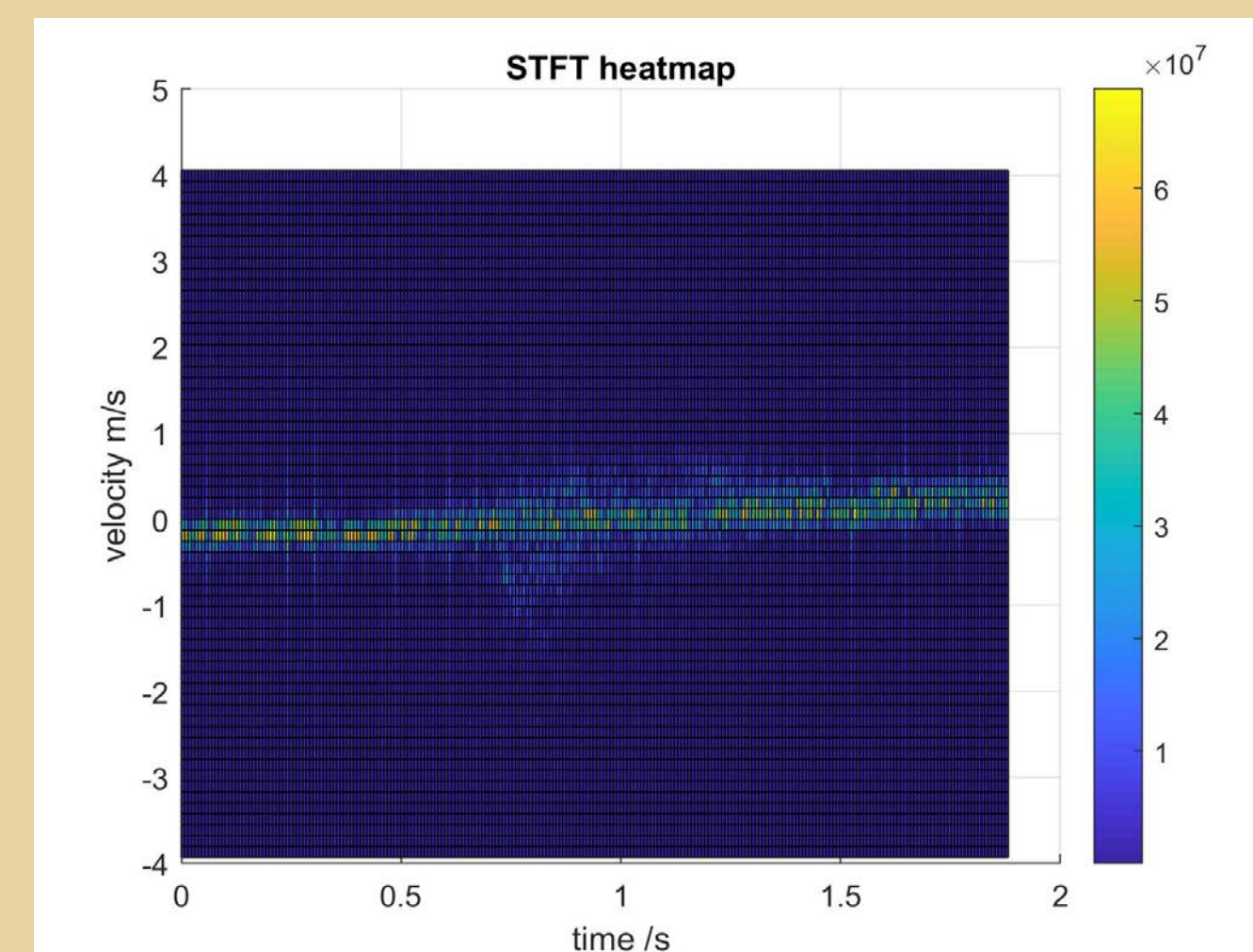
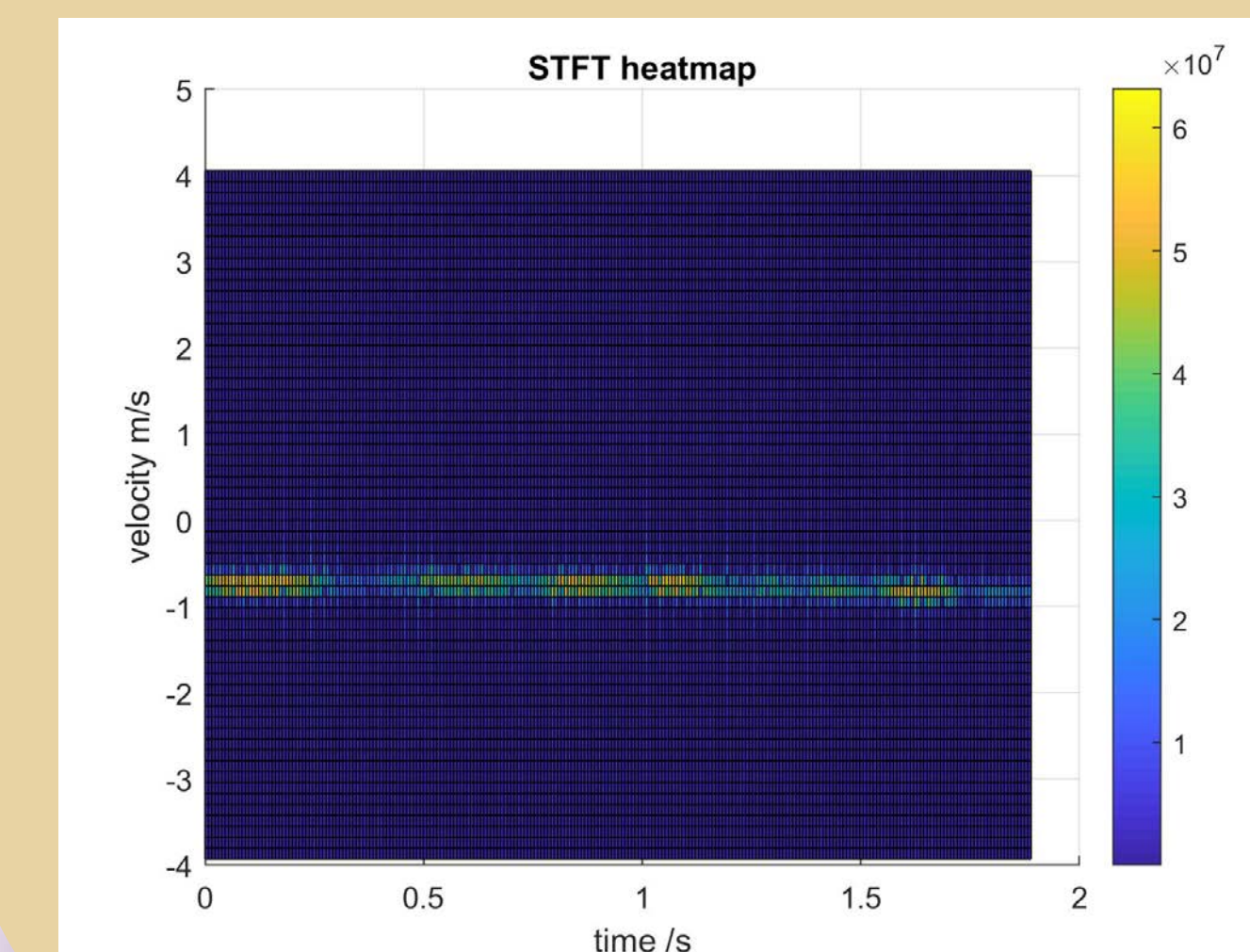
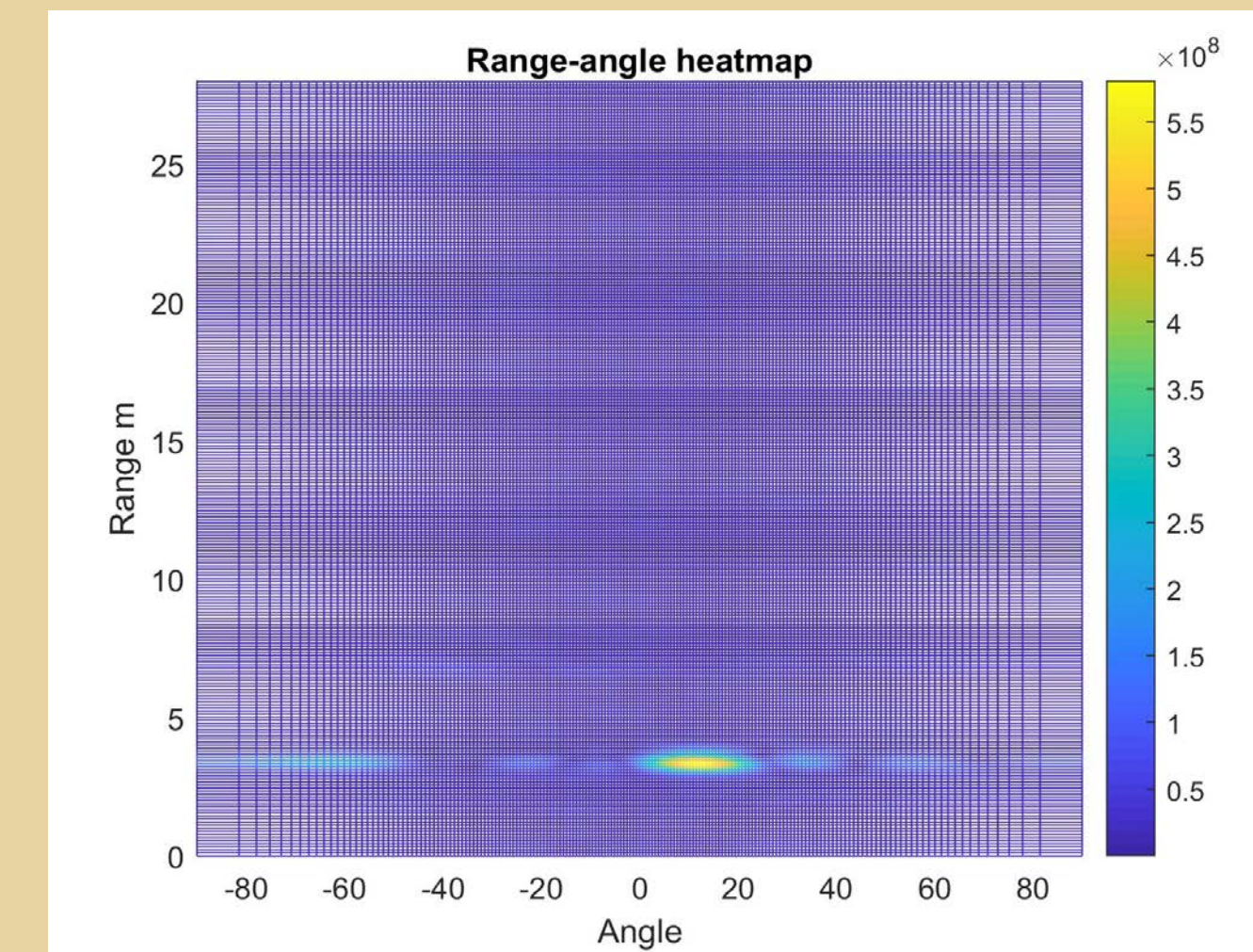
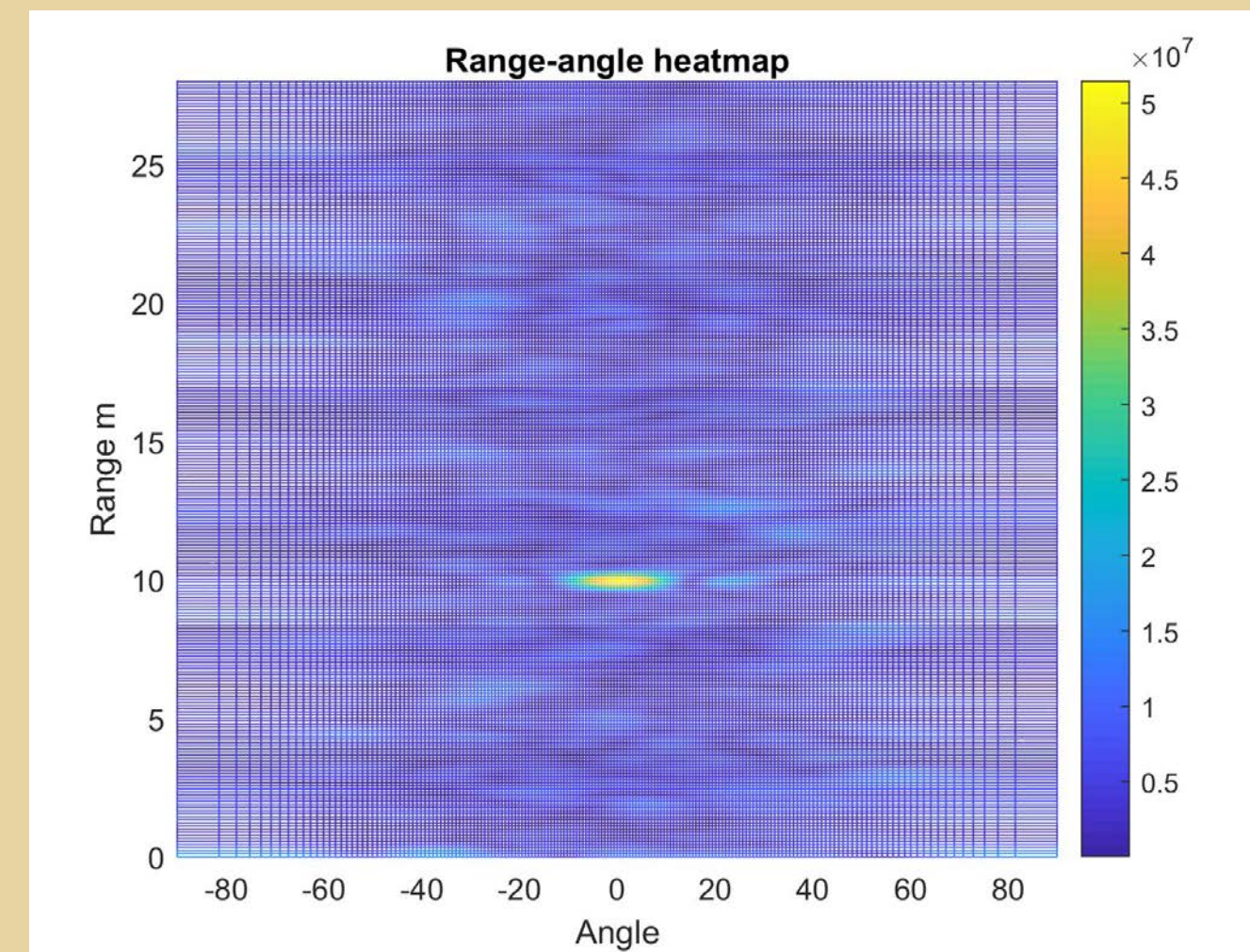
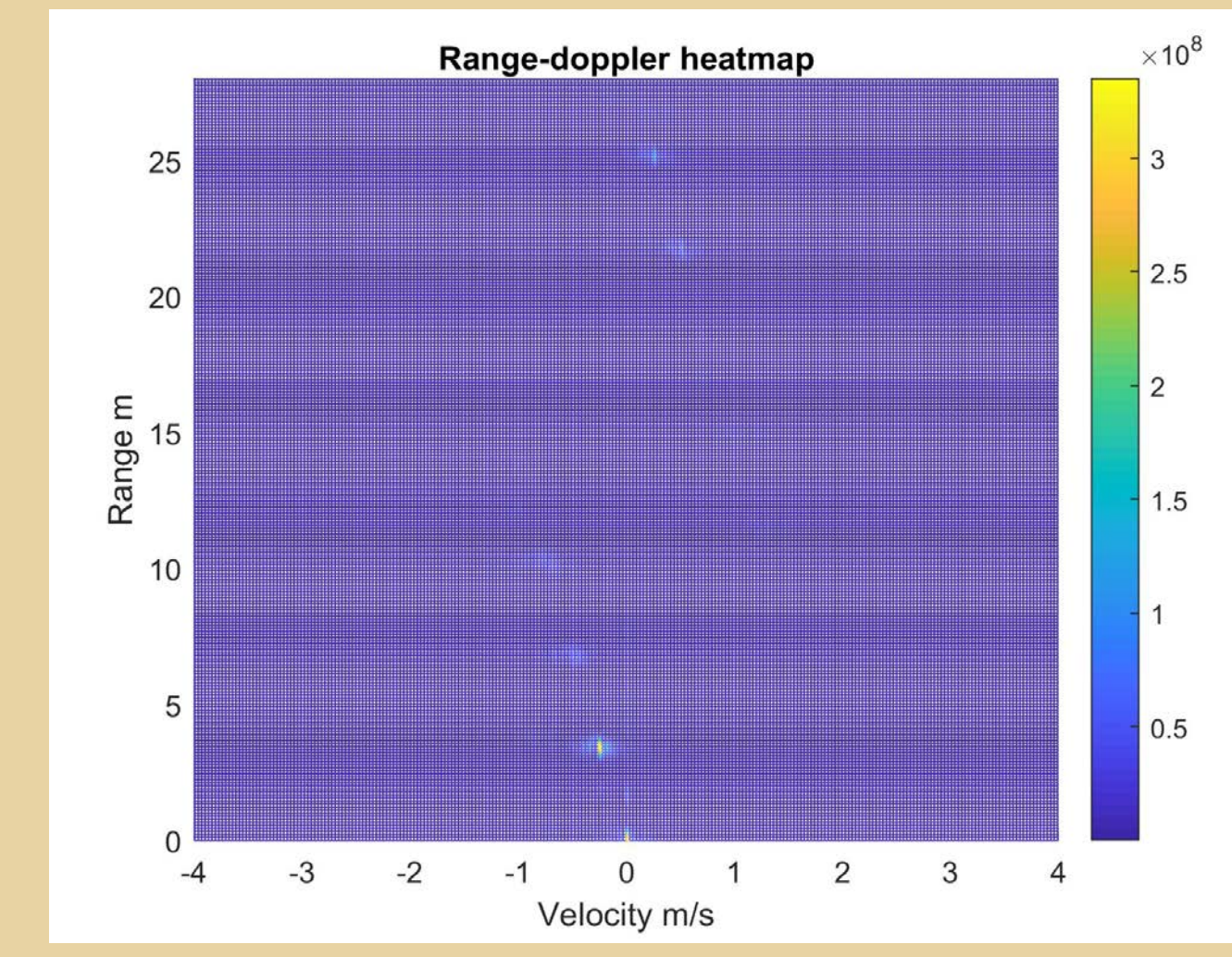
- Using raw data from radar
- Mixed Rx and Tx signal
- Applied to generate detections:
 - Fourier Transform
 - Short-Time Fourier Transform
 - Constant False Alarm Rate (CFAR)
- Using detection information, created automated processing script to create spreadsheet with data
- Classifier was trained from data gathered



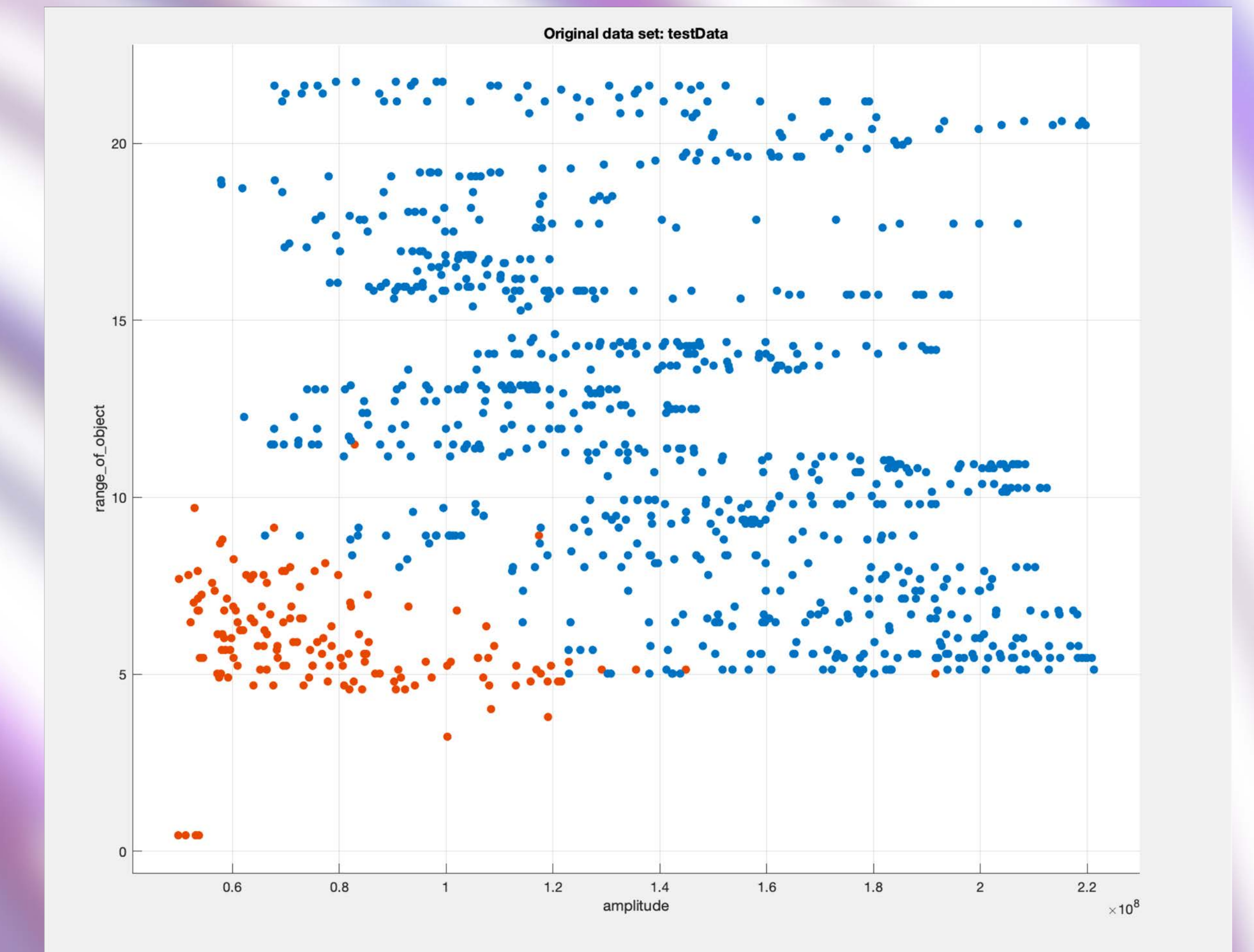
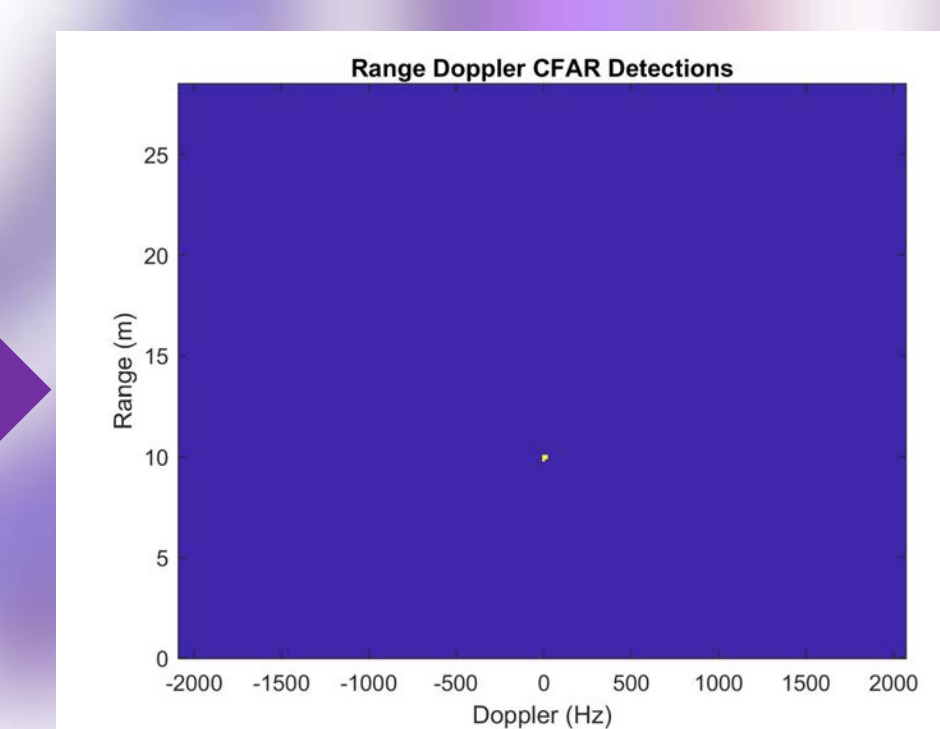
Vehicle



Pedestrian



CFAR



● Pedestrian ● Vehicle

Medium Gaussian Support Vector Machine (SVM) Classifier

- Developed using MATLAB Classification Learner APP
- Trained on 1800 samples of pedestrians and vehicle
- Based on six different features of each detection
- Accuracy: 99.4%

Conclusion

- Developed algorithms to process raw radar data and give useful information about object.
- Learned what is needed to form a useful detection
- Learned applications of Fourier transform?
- Developed classifier that predicts with high accuracy whether object is a pedestrian or a vehicle.
- Learned how to use MATLAB classification tool

Future Work

- Diversifying scenarios for algorithm testing and improving robustness
- Improvement of object classifier
 - Train using wider range of data from large set of scenarios to diversify data set
 - Improve pre-processing algorithms to improve on feature detection

Acknowledgements

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